

Conflict Equivalence of Branching Processes

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Abstract—For concurrent and large systems, specification step is a crucial point. Combinatory explosion is a limit that can be encountered when a state space exploration is driven on large specification modeled with Petri nets. Considering bounded Petri nets, technics like unfolding can be a way to cope with this problem. This paper is a first attempt to present an axiomatic model to produce the set of processes of unfoldings into a canonic form. This canonic form allows to define a conflict equivalence.

Index Terms—Petri Nets; Unfolding; Branching process; Algebra.

I. INTRODUCTION

The complexity and the criticality of some real-time system (transportation systems, robotics), but also the fact that we can no longer tolerate failures in less critical realtime systems (smartphones, warning radar devices) enforces the use of verification and validation methods. Petri nets are a widely used tool used to model critical real-time systems. The formal validation of properties is then based on the computation of state space. But, this computation faces generally, for highly concurrent and large systems, to combinatory explosion.

The specification of parallel components is generally modeled by the interleavings of the behavior of each components. This semantics of interleaving is exponentially costly in the computing of the state space. Partial order semantics have been introduced to shunt those interleavings. This semantics prevents combinatory explosion by keeping parallelism in the model.

The objective of this approach is to pursue a theoretical aspect: to speed up the identification of the branching processes of an unfolding. The notion of equivalence can be used to make a new type of reduction of unfoldings.

Finite prefixes of net unfoldings constitute a first transformation of the initial Petri Net (PN), where cycles have been flattened. This computation produces a process set where conflicts act as a discriminating factor. A conflict partitions a process in branching processes. An unfolding can be transformed into a set of finite branching processes. These

processes constitute a set of acyclic graphs - several graphs can be produced when the PN contains parallelism - built with events and conditions, and structured with two operators: causality and true parallelism. An interesting particularity of an unfolding is that, in spite of the loss of global marking, these processes contain enough information to reconstitute the reachable markings of the original Petri nets. In most of the cases, unfoldings are larger than the original Petri net. This is provoked essentially when values of precondition places exceed the precondition of non simple conflicts. This produces a lot of alternative conditions. In spite of that, a step has been taken forward: cycles have been broken and the conflicts have structured the nets in branching processes.

This paper proposes proposes an algebraic model for the definition and the reduction of the branching process of an unfolding. This paper extends [1] to reset Petri nets. Reset arcs are particularly useful, they bring expressiveness and compactness. In the example presented in the Section VI, reset arcs allow to clear the states particularly when the user has several attempts to enter its code.

A lot of works have been proposed to improve unfolding algorithms [2][3][4][5]. Is there another way to draw on recent works about unfolding? In spite of the eventual increase of the size of the net unfoldings, the suppression of conflicts and loops has decreased its structural complexity, allowing to compute the state space and to the extract of semantic information.

From a developer's point of view an unfolding can be efficiently coded by a boolean table of events. This table describes every pair to pair relation between events. This table has been the starting point of our reflection: it stresses the point that a new connector can be defined to express that a set of events belong to the same process. This connector allows to aggregate all the events of a branching process. For example, a theorem is proposed to compute all the branching processes, in canonic form, for chains of conflicts of the kind illustrated in Figure 1.

The work presented in this paper takes place in the context

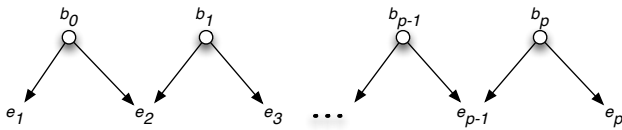


Figure 1. Chain of conflicts.

TABLE I. Process syntax.

Capacity	α	$::=$	$\bar{x} \mid x \mid \tau$
Proces	p	$::=$	$\alpha.p \mid p \mid q \mid p + q \mid D(\bar{x}) \mid p \setminus x \mid 0$

of combining process algebra [6][7] and Petri nets [8].

The axiomatic model of Milner's process with Calculus of Communicating Systems (CCS) is compared with the branching processes and related to other works in Section II. Then, after a brief presentation of Petri nets and unfoldings in Section III, Section IV presents our contribution with the definition of an axiomatic framework and the description of properties. The last section presents examples, in particular, illustrating a conflict equivalence.

II. RELATED WORK

Process algebra appeared with Milner [7] on the Calculus of Communicating Systems (CCS) and the Communicating Sequential Processes (CSP) of Hoare [6]. These approaches are not equivalent but share similar objectives. The algebra of branching process proposed in this paper is inspired by the process algebra of Milner. *CCS* is based on two central ideas: The notion of observability and the concept of synchronized communication; *CCS* is as an abstract code that corresponds to a real program whose primitives are reduced to simple send and receive on channels. The terms (or agents) are called processes with interaction capabilities that match requests communication channels. The elements of the alphabet are observable events and concurrent systems (processes). They can be specified with the use of three operators: sequence, choice, and parallelism. A main axiom of *CCS* is the rejection of distributivity of the sequence upon the choice. Let p and q be two processes, the complete syntax of process is described in the Table I.

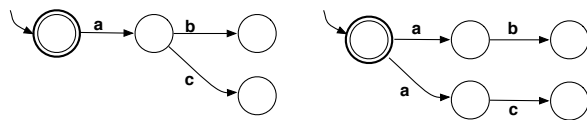


Figure 2. Milner: rejection of distributivity of sequence on choice.

Consider an observer. In the left automaton of Figure 2, after the occurrence of the action a , he can observe either b or c . In right automaton, the observation of a does not imply that b and c stay observable. The behavior of the two automata are not equivalent.

In *CCS*, Milner defines the observational equivalence. Two automata are observational equivalent if there are bisimilar.

On a algebraic point of view, the distributivity of the sequence on the choice is rejected in equation (1):

$$a.(b + c) \not\equiv_{\text{behaviorally}} a.b + a.c \quad (1)$$

The key point of our approach is based on the fact that this distributivity is not rejected in occurrence nets. The timing of the choices in a process is essential [9]. The nodes of occurrence nets are events. An event is a fired transition of the underlying Petri net. In *CCS*, an observer observes possible futures. In occurrence nets, the observer observes arborescent past. This controversy in the theory of concurrency is an important topic of linear time versus branching time. In the model, equation (2) holds:

$$a \prec (b \perp c) \equiv (a \prec b) \perp (a \prec c) \quad (2)$$

Equation (2) is a basic axiom of our algebraic model. The equivalence relation differs then from bisimulation equivalence. This relation will be defined in the following with the definition of the canonic form of an unfolding.

Branching process does not fit with process algebra on numerous other aspects. For example, a difference can be noticed about parallelism. While unfolding keeps true parallelism, process algebra considers a parallelism of interleaving. Another difference is relative to events and conditions, which are nodes of different nature in an unfolding. Conditions and events differ in term of ancestor. Every condition is produced by at most one event ancestor (none for the condition standing for m_0 , the initial marking), whereas every event may have 1 or n condition ancestor(s).

In *CCS*, there is no distinction between conditions and events. Moreover, conditions will be consumed defining processes as set of events. However, a lot of works [5][9][10] have shown the interest of an algebraic formalization: it allows the study of connectives, the compositionally and facilitates reasoning (tools like [11]). Let have two Petri nets; it is questionable whether they are equivalent. In principle, they are equivalent if they are executed strictly in the same manner. This is obviously a too restrictive view they may have the same capabilities of interaction without having the same internal implementations. These works resulted to find matches (rather flexible and not strict) between nets. Mention may be made among other the occurrence net equivalence [12], the bisimulation equivalence [13], the partial order equivalence [14], or the ST-bisimulation equivalence [15]. These different equivalences are based either on the isomorphism between the unfolding of nets or on observable actions or traces of the execution of Petri nets or other criteria.

The approach developed in this paper proposes a new equivalence, which is weaker than a trace equivalence; it does not preserves traces but preserves conflicts. The originality of the approach is to encapsulate causality and concurrency in a new operator, which "aggregates" and "abstracts" events in a process. This new operator reduces the representation and accelerates the reduction process. This paper intends first, to give an algebraic model to an unfolding, and second,

to establish a canonic form leading to the definition of an equivalence conflict.

III. UNFOLDING A PETRI NET

In this section, Petri nets and unfolding of Petri nets are presented.

A. Petri Net

A Petri net [8] $\mathcal{N} = \langle P, T, \mathcal{W} \rangle$ is a triple with: P , a finite set of places, T , the finite set of transitions, $P \cup T$ are nodes of the net; ($P \cap T = \emptyset$ signifies that P and T are disjoint), and $\mathcal{W} : (P \times T) \cup (T \times P) \rightarrow \mathcal{N}$, the flow relation defining arcs (and their valuations) between nodes of \mathcal{N} . A *marking* of \mathcal{N} is a multiset $M : P \rightarrow \{0, 1, 2, \dots\}$ and the *initial marking* is denoted M_0 .

The pre-set (resp. post-set) of a node x is denoted $\bullet x = \{y \in P \cup T \mid \mathcal{W}(y, x) > 0\}$ (resp. $x^\bullet = \{y \in P \cup T \mid \mathcal{W}(x, y) > 0\}$). A transition $t \in T$ is said *enabled* by m iff: $\forall p \in \bullet t, m(p) \geq \mathcal{W}(p, t)$. This is denoted: $m \xrightarrow{t}$ Firing of t leads to the new marking $m' (m \xrightarrow{t} m') : \forall p \in P, m'(p) = m(p) - \mathcal{W}(p, t) + \mathcal{W}(t, p)$. The initial marking is denoted m_0 .

A Petri net is *k-bounded* iff $\forall m$, reachable from $m_0, m(p) \leq k$ (with $p \in P$). It is said *safe* when *1-bounded*. Two transitions are in a *structural conflict* when they share at least one pre-set place; a conflict is *effective* when these transitions are both enabled by a same marking. The considered Petri nets in this paper are *k-bounded*.

Reset arcs constitute an extension of Petri nets. These arcs does not change the enabling rules of transitions [16]. If $Rst(p, t)$ represents the set of reset arcs from a transition t to a place p . If $M \xrightarrow{t} M'$ then $\forall p \in P$ such as $Rst(p, t) = 0, M'(p) = 0$. But if $W(t, p) > 0$ then $M'(p) = W(t, p)$. The firing rule is defined by the following relation

$$\forall p \in P, M' = (M - Pre(p, t)) \cdot R(p, t) + Post(p, t)$$

where “ \cdot ” is the Hadamard matrix product.

Definition 1 (Reset arc Petri Nets). *A reset arc Petri Nets is a tuple $N_R = \langle P, T, W, R \rangle$ with $\langle P, T, W \rangle$ a Petri nets and $Rst : P \times T \rightarrow \{0, 1\}$ is the set of reset arcs ($Rst(p, t) = 0$ is there exists a reset arc binding p to t , else $Rst(p, t) = 1$).*

B. Unfolding

In [3], the notion of *branching process* is defined as an initial part of a run of a Petri net respecting its partial order semantics and possibly including non deterministic choices (conflicts). This net is acyclic and the largest branching process of an initially marked Petri net is called *the unfolding* of this net. Resulting net from an unfolding is a labeled occurrence net, a Petri net whose places are called *conditions* (labeled with their corresponding place name in the original net) and

transitions are called *events* (labeled with their corresponding transition name in the original net).

An occurrence net [17] is a net $\mathcal{O} = \langle \mathcal{B}, \mathcal{E}, \mathcal{F} \rangle$, where \mathcal{B} is the set of *conditions* (places), \mathcal{E} is the set of *events* (transitions), and \mathcal{F} the flow relation (1-valued arcs), such that:

- for every $b \in \mathcal{B}, |\bullet b| \leq 1$;
- \mathcal{O} is acyclic;
- for every $e \in \mathcal{E}, \bullet e \neq \emptyset$;
- \mathcal{O} is finited preceded;
- no element of $\mathcal{B} \cup \mathcal{E}$ is in conflict with itself;
- \mathcal{F}^+ , the transitive closure of \mathcal{F} , is a strict order relation.

$Min(\mathcal{O}) = \{b \mid b \in \mathcal{B}, |\bullet b| = 0\}$ is the minimal conditions set: the set of conditions with no ancestor can be mapped with the initial marking of the underlying Petri net. Also, $Max(\mathcal{O}) = \{x \mid x \in \mathcal{B} \cup \mathcal{E}, |x^\bullet| = 0\}$ are maximal nodes. A *configuration* C of an occurrence net is a set of events satisfying:

- if $e \in C$ then $\forall e' \prec e$ implies $e' \in C$ (C is causally closed);
- $\forall e, e' \in C : \neg(e \perp e')$ (C is conflict-free).

A *local configuration* $[e]$ of an event e is the set of event e' , such that $e' \prec e$.

Three kinds of relations could be defined between the nodes of \mathcal{O} :

- The strict causality relation noted \prec : for $x, y \in \mathcal{B} \cup \mathcal{E}, x \prec y$ if $(x, y) \in \mathcal{F}^+$ (for example $e_3 \prec e_6$, in Figure 3.b).
- The conflict relation noted \perp : $\forall b \in \mathcal{B}$, if $e_1, e_2 \in b^\bullet$ ($e_1 \neq e_2$), then e_1 and e_2 are in *conflict relation*, denoted $e_1 \perp e_2$ (for example $e_4 \perp e_5$, in Figure 3.b).
- The concurrency relation noted \wr : $\forall x, y \in \mathcal{B} \cup \mathcal{E}$ ($x \neq y$), $x \wr y$ ssi $\neg((x \prec y) \vee (y \prec x) \vee (x \perp y))$ (for example $e_2 \wr e_3$, in Figure 3.b).

Remark 1. *The transitive aspect of \mathcal{F}^+ implies a transitive definition of strict causality.*

A set $B \subseteq \mathcal{B}$ of conditions such as $\forall b, b' \in B, b \neq b' \Rightarrow b \wr b'$ is a *cut*. Let B be a cut with $\forall b \in B, \nexists b' \in \mathcal{B} \setminus B, b \wr b', B$ is the *maximal cut*.

Definition 2. The unfolding $Unf_{\mathcal{F}} \stackrel{\text{def}}{=} \langle \mathcal{O}_{\mathcal{F}}, \lambda_{\mathcal{F}} \rangle$ of a marked net $\langle \mathcal{N}, m_0 \rangle$, with $\mathcal{O}_{\mathcal{F}} \stackrel{\text{def}}{=} \langle \mathcal{B}_{\mathcal{F}}, \mathcal{E}_{\mathcal{F}}, \mathcal{F}_{\mathcal{F}} \rangle$ an occurrence net and $\lambda_{\mathcal{F}} : \mathcal{B}_{\mathcal{F}} \cup \mathcal{E}_{\mathcal{F}} \rightarrow \mathcal{P} \cup \mathcal{T}$ (such as $\lambda(\mathcal{B}_{\mathcal{F}}) \subseteq \mathcal{P}$ and $\lambda(\mathcal{E}_{\mathcal{F}}) \subseteq \mathcal{T}$) a labeling function, is given by:

- 1) $\forall p \in \mathcal{P}$, if $m_0(p) \neq \emptyset$, then $B_p \stackrel{\text{def}}{=} \{b \in \mathcal{B}_{\mathcal{F}} \mid \lambda_{\mathcal{F}}(b) = p \wedge \bullet b = \emptyset\}$ and $m_0(p) = |B_p|$;
- 2) $\forall B_t \subseteq \mathcal{B}_{\mathcal{F}}$ such as B_t is a cut, if $\exists t \in \mathcal{T}, \lambda_{\mathcal{F}}(B_t) = \bullet t \wedge |B_t| = |\bullet t|$, then:
 - a) $\exists! e \in \mathcal{E}_{\mathcal{F}}$ such as $\bullet e = B_t \wedge \lambda_{\mathcal{F}}(e) = t$;
 - b) if $t^\bullet \neq \emptyset$, then $B'_t \stackrel{\text{def}}{=} \{b \in \mathcal{B}_{\mathcal{F}} \mid \bullet b = \{e\}\}$ is as $\lambda_{\mathcal{F}}(B'_t) = t^\bullet \wedge |B'_t| = |t^\bullet|$;
 - c) if $t^\bullet = \emptyset$, then $B'_t \stackrel{\text{def}}{=} \{b \in \mathcal{B}_{\mathcal{F}} \mid \bullet b = \{e\}\}$ is as $\lambda_{\mathcal{F}}(B'_t) = \emptyset \wedge |B'_t| = 1$;

- 3) $\forall B_t \subseteq \mathcal{B}_F$, if B_t is not a cut, then $\nexists e \in \mathcal{E}_F$ such as $\bullet e = B_t$.

Definition 2 represents an *exhaustive* unfolding algorithm of $\langle \mathcal{N}, m_0 \rangle$. In 1., the algorithm for the building of the unfolding starts with the creation of conditions corresponding to the initial marking of $\langle \mathcal{N}, m_0 \rangle$ and in 2., new events are added one at a time together with their output conditions (taking into account sink transitions). In 3., the algorithm requires that any event is a possible action: there are no adding nodes to those created in items 1 and 2. The algorithm does not necessary terminate; it terminates if and only if the net $\langle \mathcal{N}, m_0 \rangle$ does not have any infinite sequence. The sink transitions (ie $t \in \mathcal{T}, t^\bullet = \emptyset$) are taken into account in 2.(c).

Let be $\mathcal{E} \subset \mathcal{E}_F$. The occurrence net $\mathcal{O} \stackrel{\text{def}}{=} \langle \mathcal{B}, \mathcal{E}, \mathcal{F} \rangle$ associated with \mathcal{E} such as $\mathcal{B} \stackrel{\text{def}}{=} \{b \in \mathcal{B}_F \mid \exists e \in \mathcal{E}, b \in \bullet e \cup e^\bullet\}$ and $\mathcal{F} \stackrel{\text{def}}{=} \{(x, y) \in \mathcal{F}_F \mid x \in \mathcal{E} \vee y \in \mathcal{E}\}$ is a prefix of \mathcal{O}_F if $\text{Min}(\mathcal{O}) = \text{Min}(\mathcal{O}_F)$. By extension, $\text{Unf} \stackrel{\text{def}}{=} \langle \mathcal{O}, \lambda \rangle$ (with λ , the restriction of λ_F to $\mathcal{B} \cup \mathcal{E}$) is a prefix of unfolding Unf_F .

It should be noted that, according to the implementation, the names (the elements in the sets \mathcal{E} and \mathcal{B}) given to nodes in the same unfolding can be different. A name can be independently chosen in an implementation using a tree formed by its causal predecessors and the name of the corresponding nodes in \mathcal{N} [3].

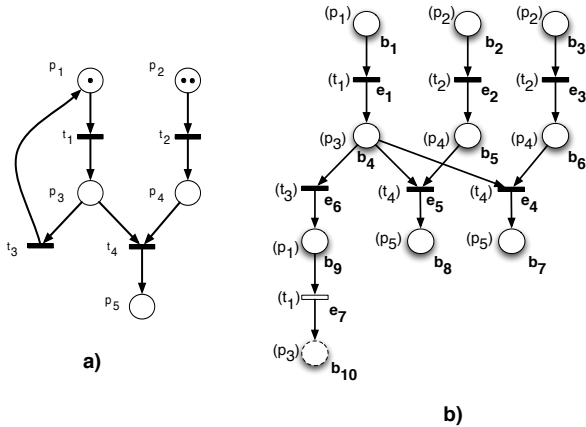


Figure 3. a) Petri net, b) Unfolding.

Definition 3. A causal net \mathcal{C} is an occurrence net $\mathcal{C} \stackrel{\text{def}}{=} \langle \mathcal{B}, \mathcal{E}, \mathcal{F} \rangle$ such as:

- 1) $\forall e \in \mathcal{E} : e^\bullet \neq \emptyset \wedge \bullet e \neq \emptyset$;
- 2) $\forall b \in \mathcal{B} : |b^\bullet| \leq 1 \wedge |\bullet b| \leq 1$.

Definition 4. $\mathcal{P}_i = (\mathcal{C}_i, \lambda_F)$ is a process of $\langle \mathcal{N}, m_0 \rangle$ iff: $\mathcal{C}_i \stackrel{\text{def}}{=} \langle \mathcal{B}_i, \mathcal{E}_i, \mathcal{F}_i \rangle$ is a causal net and $\lambda : \mathcal{B}_i \cup \mathcal{E}_i \rightarrow P \cup T$ is a labeling fonction such as:

- 1) $\mathcal{B}_i \subseteq \mathcal{B}_F$ and $\mathcal{E}_i \subseteq \mathcal{E}_F$
- 2) $\lambda_F(\mathcal{B}_i) \subseteq P$ and $\lambda_F(\mathcal{E}_i) \subseteq T$;
- 3) $\lambda_F(\bullet e) = \bullet \lambda_F(e)$ and $\lambda_F(e^\bullet) = \lambda_F(e)^\bullet$
- 4) $\forall e_i \in \mathcal{E}_i, \forall p \in P : \mathcal{W}(p, \lambda_F(e)) = |\lambda^{-1}(p) \cap \bullet e| \wedge \mathcal{W}(\lambda_F(e), p) = |\lambda^{-1}(p) \cap e^\bullet|$

- 5) If $p \in \text{Min}(P) \Rightarrow \exists b \in \mathcal{B}_i : \bullet b = \emptyset \wedge \lambda_F(b) = p$

$\text{Max}(\mathcal{C}_i)$ is the state of \mathcal{N} . $\text{Min}(\mathcal{C}_i)$ and $\text{Max}(\mathcal{C}_i)$ are (resp. minimum) maximum cuts. Generally, any maximal cut $B \subseteq \mathcal{B}_i$ corresponds to a reachable marking m of $\langle \mathcal{N}, m_0 \rangle$ such as $\forall p \in \mathcal{P}, m(p) = |B_p|$ avec $B_p = \{b \in B \mid \lambda(b) = p\}$.

The *local configuration* of an event e is defined by: $[e] \stackrel{\text{def}}{=} \{e' \mid e' \prec e\} \cup \{e\}$ and is a process. For example of unfolding in Figure 3.b: $[e_4] \stackrel{\text{def}}{=} \{e_1, e_3, e_4\}$.

The conflicts in an unfolding derive from the fact that there is a reachable marking (a cut in an unfolding) such as two or many transitions of a labelled net $\langle \mathcal{N}, m_0 \rangle$ are *enabled* and the firing of one transition disable other. Whence the proposition:

Proposition 1. Let be $e_1, e_2 \in \mathcal{E}_F$. If $e_1 \perp e_2$, then there $\exists (e'_1, e'_2) \in [e_1] \times [e_2]$ such as $\bullet e'_1 \cap \bullet e'_2 \neq \emptyset$ et $\bullet e'_1 \cup \bullet e'_2$ is a cut.

IV. BRANCHING PROCESS ALGEBRA

The Section III-B showed how unfolding exhibits causal nets and conflicts. Otherwise, every couple of events that are not bounded by a causal relation or the same conflict set are in concurrency. Then, an unfolding allows to build a 2D-table making explicit every binary relations between events. Practically, this table establishes the relations of causality and exclusion. If a binary relation is not explicit in the table, it means that the couple of events are in a concurrency relation.

Let $\mathcal{EB} = \mathcal{E} \cup \mathcal{B}$ a finite alphabet, composed of the events and the conditions generated by the unfolding. The event table (produced by the unfolding) defines for every couple in \mathcal{EB} either a causality relation \mathcal{C} , either a concurrency relation \mathcal{I} or an exclusive relation \mathcal{X} . These sets of binary relations dot not intersect and the following expressions can be deduced:

$$\text{Unf}/\mathcal{X} = \mathcal{C} \cup \mathcal{I} \quad (3)$$

$$\text{Unf}/\mathcal{C} = \mathcal{X} \cup \mathcal{I} \quad (4)$$

$$\text{Unf}/\mathcal{I} = \mathcal{C} \cup \mathcal{X} \quad (5)$$

To illustrate these relation sets, the negation operator noted \neg can be introduced. Then, equations (3), (4), (5) lead to (6), (7), (8):

$$\neg((e_1, e_2) \in \mathcal{I}) \Leftrightarrow (e_1, e_2) \in \mathcal{C} \cup \mathcal{X} \quad (6)$$

$$\neg((e_1, e_2) \in \mathcal{C}) \Leftrightarrow (e_1, e_2) \in \mathcal{I} \cup \mathcal{X} \quad (7)$$

$$\neg((e_1, e_2) \in \mathcal{X}) \Leftrightarrow (e_1, e_2) \in \mathcal{C} \cup \mathcal{I} \quad (8)$$

Equation (8) expresses that if two events are not in conflict they are in the same branching process. Let us now define the union of binary relations \mathcal{C} and \mathcal{I} : $\mathcal{P} = \mathcal{C} \cup \mathcal{I}$. For every couple $(e_1, e_2) \in \mathcal{P}$, either (e_1, e_2) are in causality or in concurrency: \mathcal{P} is the union of every branching process of an unfolding.

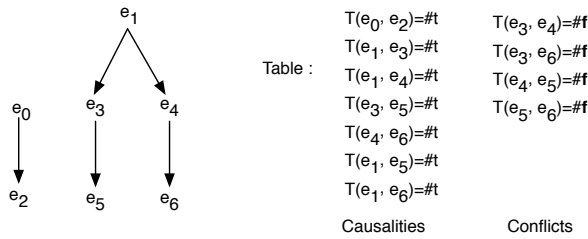


Figure 4. Unfolding.

a) *Example*: Figure 4 represents an unfolding (in the left part) and a Table T (right part), which defines the event relations of the unfolding.

In Figure 4, the Table T contains 7 causal relations and 4 conflict relations. (e_0, e_4) is not (negation) in the table, it means that e_0 and e_4 are concurrent. Moreover, if two events are not in conflict (consider e_0 and e_6): (e_0, e_6) is not a key of the table, (e_0, e_6) are in concurrency and thus, those events belongs to the same branching process.

A. Definition of the Algebra

The starting point of this work is based on the fact that the logical negation operator articulates the relation between two sets: the process set \mathcal{P} and the exclusion set \mathcal{X} . As mentioned in Section IV, \mathcal{C} , \mathcal{I} and \mathcal{P} does not intersect, then semantically, if a couple of events is not in a relation of exclusion (noted \perp), the events are in \mathcal{P} . \mathcal{P} contains binary relations between events that are in branching process.

To express that events are in the same branching process, a new operator noted \oplus is introduced. An algebra describing branching process can be defined as follow:

$$\{\mathcal{U}, \prec, \lambda, \perp, \oplus, \neg\}$$

Let us note; $*$ = \oplus , \prec , or \perp , $\#t$ the void process, and $\#f$ the false process. Here is the formal signature of the language:

- $\forall e \in \mathcal{EB}, e \in \mathcal{U}, \#t \in \mathcal{U}, \#f \in \mathcal{U}$
- $\forall e \in \mathcal{U}, \neg e \in \mathcal{U}$
- $\forall (e_1, e_2) \in \mathcal{U}^2, e_1 * e_2 \in \mathcal{U}$.

B. Definition of operators

1) *Causality*: \mathcal{C} is the set of all the causalities between every elements of \mathcal{EB} . $e_1 \prec e_2$ if e_1 is in the local configuration of e_2 , i.e., the Petri net contains a path with at least one arc leading from e_1 to e_2 :

$$e_1 \prec e_2 \text{ if } e_1 \in [e_2] \quad (9)$$

- \prec is associative: $e_1 \prec (e_3 \prec e_5) \equiv (e_1 \prec e_3) \prec e_5$;
- \prec is transitive: $(e_1 \prec e_3) \vee (e_3 \prec e_5) \equiv e_1 \prec e_5$;
- \prec is not commutative: $e_1 \prec e_3$ but $e_3 \not\prec e_1$;
- $\#t$ is the neutral element for \prec : $\#t \prec e \equiv e$;
- every element of \mathcal{EB} has an opposite: $\#f \prec e \equiv \neg e$.

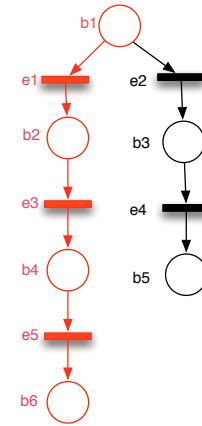


Figure 5. Causalite.

2) *Exclusion*: \mathcal{X} is the set of all the exclusion relations between every elements of \mathcal{EB} . Two events e and e' are in exclusion if the net contains two paths $b e_1 \dots e$ and $b e_2 \dots e'$ starting at the same condition b and $e_1 \neq e_2$:

$$e_1 \perp e_2 \equiv ((\bullet e_1 \cap \bullet e_2 \neq \emptyset) \text{ or } (\exists e_i, e_i \prec e_2 \text{ and } e_1 \perp e_i)) \quad (10)$$

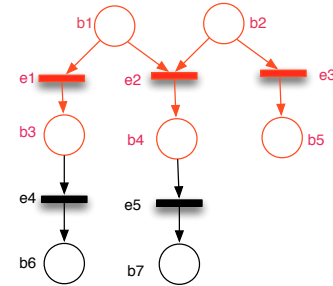


Figure 6. Exclusion.

- \perp is commutative: $e_1 \perp e_2 \equiv e_2 \perp e_1$;
- \perp is associative: $e_1 \perp (e_2 \perp e_3) \equiv (e_1 \perp e_2) \perp e_3$;
- \perp is not transitive: $(e_1 \perp e_2) \vee (e_2 \perp e_3)$ but $e_1 \not\perp e_3$;
- $\#f$ is the neutral element for \perp : $e \perp \#f \equiv e$;
- $\#t$ is the absorbing element for \perp : $e \perp \#t \equiv \#t$.

3) *Concurrency*: \mathcal{I} is the set of every couple of element of \mathcal{EB} in concurrency. e_1 and e_2 are in concurrency if the occurrence of one is independent of the occurrence of the other. So, $e_1 \lambda e_2$ iff e_1 and e_2 are neither in causality neither in exclusion.

$$e_1 \lambda e_2 \equiv \neg((e_1 \perp e_2) \text{ or } (e_1 \prec e_2) \text{ or } (e_2 \prec e_1)) \quad (11)$$

- λ is commutative: $e_1 \lambda e_5 \equiv e_5 \lambda e_1$;
- λ is associative: $e_1 \lambda (e_5 \lambda e_7) \equiv (e_1 \lambda e_5) \lambda e_7$;
- λ is not transitive: $(e_1 \lambda e_5) \vee (e_5 \lambda e_2)$ but $e_1 \not\lambda e_2$;
- $\#t$ is the neutral element for λ : $e \lambda \#t \equiv e$;
- $\#f$ is an absorbing element for λ : $e \lambda \#f \equiv \#f$.

4) *Process*: \oplus aggregates events in one process. Two events e_1 and e_2 are in the same process if e_1 causes e_2 or if e_1 is

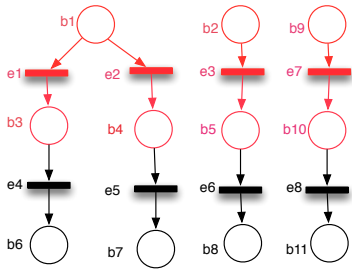


Figure 7. Concurrency.

concurrent with e_2 :

$$e_1 \oplus e_2 \equiv (e_1 \prec e_2) \text{ or } (e_2 \prec e_1) \text{ or } (e_1 \lambda e_2) \quad (12)$$

This operator constitutes an abstraction that hides in a black box causalities and concurrencies. The meaning of this operator is similar to the linear connector \oplus of MILL [18]. It allows to aggregates resources. But, in the context of unfolding, events or conditions are unique and then they cannot be counted. Thus, this operator is here idempotent.

The expression $e_1 \oplus e_2$ defines that e_1 and e_2 are in the same process.

Note that $(\oplus e_1 e_2 \dots e_{n-1} e_n)$ will abbreviate $(e_1 \oplus e_2 \oplus e_3 \oplus \dots e_{n-1} \oplus e_n)$

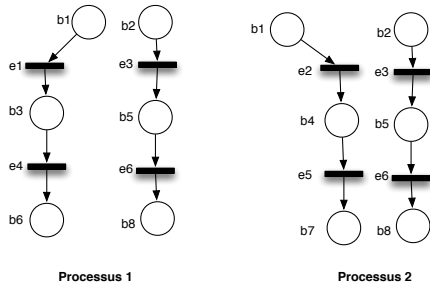


Figure 8. Process.

- \oplus is commutative, associative, and transitive (definition of \oplus);
- Idempotency: $e \oplus e \equiv e$
- Neutral element: $e \oplus \#t \equiv e$
- Absorbing element: $e \oplus \#f \equiv \#f$
- $e \oplus \neg e \equiv \#f$

C. Axioms

The following axioms stem directly from previous assumptions and definitions made upon the algebraic model:

Axiom 1 (Distributivity of \prec).

$$e \prec (e_1 \perp e_2) \equiv_{def} (e \prec e_1) \perp (e \prec e_2)$$

This first axiom constitutes the basis of our approach. As discussed in the Section II, on the contrary of *CCS*, e is distributed onto two expressions, giving alternative processes.

Axiom 2 (Definition of \oplus).

$$e_1 \oplus e_2 \equiv_{def} (e_1 \prec e_2) \perp (e_2 \prec e_1) \perp (e_1 \lambda e_2)$$

\oplus aggregates two elements in a process. Two elements are in a process if they are concurrent or in a causality relation.

Axiom 3 (\prec).

$$e_1 \prec e_2 \equiv_{def} \neg e_1 \perp (e_1 \oplus e_2)$$

A causality can be expressed by two processes in exclusion: either $\neg e_1$: e_1 has not occurred either $e_1 \oplus e_2$: e_1 and e_2 within the same process.

Axiom 4 (Duality between \oplus and \perp).

$$e_1 \oplus e_2 \equiv_{def} e_1 \neg e_2 \quad e_1 \neg e_2 \equiv_{def} e_1 \perp e_2$$

This axiom comes from the introduction of the operator \neg discussed in the beginning of the Section IV. It expresses that \mathcal{P} and \mathcal{X} are complementary sets.

Axiom 5 (Exclusion).

$$e_1 \perp e_2 \equiv_{def} (\neg e_1 \oplus e_2) \perp (e_1 \oplus \neg e_2)$$

The fifth axiom expresses that a conflict can be considered as two processes in conflict.

D. Distributivities

The distributivities over \perp are used in the transformation of an expression in the canonical form (Section V). The other distributivities will be used in the reduction process.

1) Distributivities over λ :

- \prec is distributive over λ :

$$e \prec (e_1 \lambda e_2) \equiv (e \prec e_1) \lambda (e \prec e_2)$$

- \perp is distributive over λ :

$$e \perp (e_1 \lambda e_2) \equiv (e \perp e_1) \lambda (e \perp e_2)$$

- \oplus is distributive over λ :

$$e \oplus (e_1 \lambda e_2) \equiv (e \oplus e_1) \lambda (e \oplus e_2)$$

2) Distributivities over \perp :

- \prec is distributive over \perp (Axiom 1):

$$e \prec (e_1 \perp e_2) \equiv (e \prec e_1) \perp (e \prec e_2)$$

- λ is distributive over \perp :

$$e \lambda (e_1 \perp e_2) \equiv (e \lambda e_1) \perp (e \lambda e_2)$$

- \oplus is distributive over \perp :

$$e \oplus (e_1 \perp e_2) \equiv (e \oplus e_1) \perp (e \oplus e_2)$$

3) *Distributivities over* \oplus :

- \perp is distributive over \oplus :

$$e \perp (e_1 \oplus e_2) \equiv (e \oplus e_1) \perp (e \oplus e_2)$$

- \wr is distributive over \oplus :

$$e \wr (e_1 \oplus e_2) \equiv (e \oplus e_1) \wr (e \oplus e_2)$$

E. *Derivation Rules*

This section gives a set of rules, which transform branching processes toward a canonical form. These transformations preserve conflicts whereas \prec and \wr are transformed in \oplus .

Let us note b a condition, e an event and E a well formed formula on the algebra. These rules allow to reduct process:

1) *Modus Ponens*:

$$\frac{\vdash \oplus b \dots \quad \vdash \oplus b \dots \prec e}{\vdash e} MP_1$$

$$\frac{\vdash e \quad \vdash e \prec \oplus b \dots}{\vdash \oplus e b \dots} MP_2$$

Where $\oplus b \dots$ stands for the general form for $(\oplus b_1 b_2 \dots b_n)$. MP_1 expresses that the set of conditions $\oplus b \dots$ are consumed by the causality, whereas in MP_2 , e stays in the conclusion.

2) *Dual form*:

$$\frac{\vdash \neg e_1 \quad \vdash e_1 \prec e_2}{\vdash \neg e_1 \oplus \neg e_2} MP'$$

3) *Simplification*:

$$\frac{\vdash \neg e_1 \oplus E}{\vdash E} S_1$$

$$\frac{\vdash \oplus b \dots E}{\vdash E} S_2$$

Those rules are applied, *in fine*, to clear not pertinent informations in the process. S_1 rule is applied, to clear the negations, whereas S_2 is applied to clear the conditions, which have not been consumed.

4) *Reduction of* \wr :

$$\frac{\vdash e_1 \wr e_2}{\vdash e_1 \oplus e_2} Par$$

This rule corresponds to the definition of \oplus . These rules have been defined to lead to a canonic form.

V. CANONIC FORM AND CONFLICT EQUIVALENCE

A *canonic form* is a relation expressed on elements of \mathcal{EB} and with the operators \oplus and \perp ordered by an alphanumeric sort on the name of its symbol. This definition of the canonic form allows to define an equivalence called a “conflict equivalence”.

Theorem 1 (Canonical form). *Let us consider an unfolding U , this form can be reduced in the following form:*

$$U = (\perp P_1 P_2 \dots P_n), \text{ where } P_i = (\oplus e_{i_1} \dots e_{i_n})$$

This form is canonic and exhibits every processes P_i of the unfolding.

Proof. In an unfolding every causality (\prec) and every partial order (\wr) can be reduced in \oplus by deduction rules Modus Ponens (MP, MP_1, MP_2), Simplification rule (S) and *Par* (see Section IV-E).

Moreover, \oplus and \perp are mutually distributive, so \perp can be factorized in every sub-formula to reach the higher level of the formula. In fine, an alphanumeric sort on symbols of the processes can be applied to assure the unicity of the form. \square

This canonic form preserves conflicts, let us now define a *conflict equivalence*:

Definition 5 (Conflict Equivalence). *Let us U_1, U_2 unfoldings of Petri nets:*

$$U_1 \approx_{conf} U_2 \quad \text{iff they have the same canonic form.}$$

Remark 2. *A process is an aggregate set of events, where \prec and \wr are hidden. This equivalence is lower than a trace equivalence: each process P_i is an abstraction of a set of traces.*

A. *Theorems*

The properties of operators (definitions, axioms and distributivities) allow to define theorems, which are congruences.

Theorem 2 (Conflict).

$$e_1 \prec (e_2 \perp e_3) \equiv (e_1 \prec (e_2 \oplus \neg e_3)) \perp (e_1 \prec (\neg e_2 \oplus e_3))$$

Proof.

$$\begin{aligned} e_1 \prec (e_2 \perp e_3) &\equiv_{Ax_5} e_1 \prec ((e_2 \oplus \neg e_3) \perp (\neg e_2 \oplus e_3)) \\ &\equiv_{dist} (e_1 \prec (e_2 \oplus \neg e_3)) \perp (e_1 \prec (\neg e_2 \oplus e_3)) \end{aligned}$$

\square

This theorem expresses how to develop a conflict and the following theorem allows to reduce processes:

Theorem 3 (Absorption). *Let E, F some processes:*

$$E \perp (E \oplus F) \equiv E \oplus F$$

Proof.

$$\begin{aligned} E \perp (E \oplus F) &\equiv (E \oplus \#t) \perp (E \oplus F) \\ &\equiv_{Neutral} E \oplus (\#t \perp F) \\ &\equiv E \oplus F \end{aligned}$$

□

B. Chain of conflicts

This section presents a theorem that computes the branching process in canonic form of a chain of conflict illustrated in Figure 9.

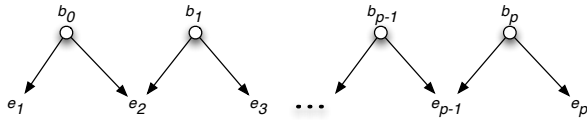


Figure 9. Chain of conflicts.

The axiomatic representation of the unfolding is:

$$U = ((\oplus b_0 b_1 \dots (b_0 \prec (e_1 \perp e_2))(b_1 \prec (e_2 \perp e_3))\dots)$$

After some steps of reduction ($MP + S$):

$$U = (e_1 \perp e_2 \perp \dots \perp e_p)$$

Let us note:

- $l^1 = (e_1, e_2, \dots, e_n)$, $l^2 = (e_2, \dots, e_n)$
- l_i the i^{th} element of a list l .
- If e_i is an element of the list l , let us note $indice(e_i)$ the position of e_i in l .

Remark 3. In the list of event constituting a chain of conflict ($l = (e_1, e_2, \dots, e_n)$), for every event e_i , the next (resp. previous) event in the same branching process is e_{i+2} or e_{i+3} (resp. e_{i-2} or e_{i-3})

The next definition defines two processes U_n and V_n , which are aggregation of events, where the possible successor of an event e_i is either $l_{(indice(e_i)+2)}$ either $l_{(indice(e_i)+3)}$.

Definition 6. Let us consider that $n \leq p$,

$$\left\{ \begin{array}{l} U_0 = e_1 \\ U_n^1 = l_{n+2}^1 \oplus U_{n+2}^2 \\ U_n^2 = l_{n+3}^1 \oplus U_{n+3}^2 \\ U_n = U_n^1 \oplus U_n^2 \end{array} \right. \quad \left\{ \begin{array}{l} V_0 = e_2 \\ V_n^1 = l_{n+2}^2 \oplus V_{n+2}^2 \\ V_n^2 = l_{n+3}^2 \oplus V_{n+3}^2 \\ V_n = V_n^1 \oplus V_n^2 \end{array} \right.$$

U_n : processes beginning by e_1 V_n : processes beginning by e_2
where p is the index of the last event implied in the chain of conflict

Theorem 4. The canonic form of a chain of conflict C is $U_n \oplus V_n$:

$$(e_1 \perp e_2 \perp \dots \perp e_p) \equiv U_n \oplus V_n$$

Proof. Correctness: let us consider an incorrect process $q \in L_p$:

$$q = (\oplus e_{q_1} e_{q_2} \dots e_{q_p})$$

An incorrect process contains two event in conflict. Thus, this incorrectness implies the existence of two events in q such as $e_{q_i} \perp e_{q_{i+1}}$ and $e_{q_i}, e_{q_{i+1}}$ corresponding to two successive events of l . This is in contradiction with the definition of the functions $(U_n^1, U_n^2, V_n^1, V_n^2)$ for which events are added with either l_{n+2} either l_{n+3} . For a correct process, indices cannot be consecutive.

Completeness: let us consider a valid process:

$$q = (\oplus e_{q_1} e_{q_2} \dots e_{q_p})$$

which is not included in L_p . $\forall e \in q$, if q is valid then $\forall (e_i, e_j) \in q, \neg(e_i \perp e_j)$, so it implies that e_i and e_j are not successive in l and every enabled event is in q . Moreover, as q is not included in L_p , thus, it exists at least one couple (e_{q_i}, e_{q_j}) , which does not correspond to the construction defined by the functions $(U_n^1, U_n^2, V_n^1, V_n^2)$, which define the possible successor of an event. This means that $indice(e_{q_j}) > indice(e_{q_i} + 3)$.

For every $n = indice(e_{q_j}) - indice(e_{q_i})$ greater than 3, let us note $i_2 = indice(e_{q_i}) + 2$ the event $e_{q_{i_2}}$ is a possible event, which is not in q (contradiction). □

VI. EXAMPLES

Examples VI-A and VI-B illustrate conlfit equivalence, whereas the example VI-C contains reset arcs.

A. Example 1

Figure 10 gives a Petri net, which represents a chain of conflicts and its unfolding.

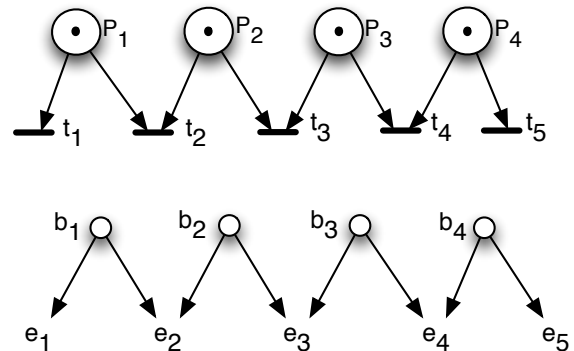


Figure 10. PN and unfolding of a chain of conflicts.

The unfolding gives a table of binary relations on events (see Section IV), which is represented by the following algebraic expression U_2 :

$$U_1 = (\oplus b_1 b_2 b_3 b_4 b_5 (b_1 \prec (e_1 \perp e_2)) (b_2 \prec (e_2 \perp e_3)) \dots)$$

After some steps of reduction ($MP + S$), U_1 becomes:

$$(e_1 \perp e_2 \perp e_3 \perp e_4 \perp e_5) \quad (13)$$

Theorem 4 allows to compute from (13) its following canonic form:

$$(\perp (\oplus e_1 e_3 e_5)(\oplus e_1 e_4)(\oplus e_2 e_4)(\oplus e_2 e_5))$$

B. Example 2

Let us consider the following Unfolding of Figure 11. The

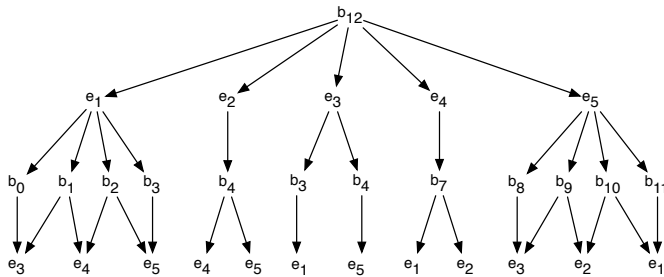


Figure 11. U_2 .

table has been computed and the set of binaries relations between events leads to the following algebraic expression U_2 :

$$\begin{aligned} U_2 = & (\oplus b_{12} \quad (b_{12} \prec (e_1 \perp e_2 \perp e_3 \perp e_4 \perp e_5)) \\ & (e_1 \prec (\oplus b_0 b_1 b_2 b_3))(e_2 \prec b_4)(e_3 \prec (\oplus b_5 b_6)) \\ & (e_5 \prec (\oplus b_8 b_9 b_{10} b_{11}))((\oplus b_0 b_1) \prec e_3) \\ & ((\oplus b_1 b_2) \prec e_4) (e_4 \prec b_7) ((\oplus b_2 b_3) \prec e_5) \\ & (b_4 \prec (\perp e_4 e_5))(b_5 \prec e_1) (b_6 \prec e_5) \\ & (b_7 \prec (\perp e_1 e_2)) ((\oplus b_8 b_9) \prec e_3) \\ & ((\oplus b_9 b_{10}) \prec e_2) ((\oplus b_{10} b_{11}) \prec e_1)) \quad (14) \end{aligned}$$

Let us note P the aggregation of the five first lines of the previous Equation (14) becomes:

$$U_2 = (\oplus b_{12} \quad (b_{12} \prec (\perp e_1 e_2 e_3 e_4 e_5)) P) \quad (15)$$

Rules MP_1 , MP_2 and theorem 1 reduce (15) in:

$$U_2 = (\perp (\oplus e_1 P) (\oplus e_2 P) (\oplus e_3 P) (\oplus e_4 P) (\oplus e_5 P))$$

Distributivity of $perp$:

$$\begin{aligned} U_2 = & (\oplus \quad (\perp (\oplus e_1 b_0 b_1 b_2 b_3)(\oplus e_2 b_4)(\oplus e_3 b_5 b_6) \\ & (\oplus e_4 b_7)(\oplus e_5 b_8 b_9 b_{10} b_{11})) ((\oplus b_0 b_1) \prec e_3) \\ & ((\oplus b_1 b_2) \prec e_4)((\oplus b_2 b_3) \prec e_5) (b_4 \prec (\perp e_4 e_5)) \\ & (b_5 \prec e_1) (b_6 \prec e_5)(b_7 \prec (\perp e_1 e_2)) \\ & ((\oplus b_8 b_9) \prec e_3) ((\oplus b_9 b_{10}) \prec e_2) \\ & ((\oplus b_{10} b_{11}) \prec e_1)) \end{aligned}$$

Distributivity of \perp and MP_1 :

$$\begin{aligned} U_2 = & (\perp \quad (\oplus e_1 e_3 e_5 b_1 b_2)(\oplus e_1 e_4 b_0 b_3)(\oplus e_2 e_4) \\ & (\oplus e_2 e_5) (\oplus e_3 e_1)(\oplus e_3 e_5)(\oplus e_4 e_1) \\ & (\oplus e_4 e_2)(\oplus e_5 e_1 e_3 b_9 b_{10}) (\oplus e_5 e_2 b_8 b_{11})) \end{aligned}$$

Theorem 2 : absorption of $(\oplus e_3 e_1)$ and $(\oplus e_3 e_5)$ in $(\oplus e_1 e_3 e_5 b_1 b_2)$, idempotency of \perp :

$$\begin{aligned} U_2 = & (\perp \quad (\oplus e_1 e_3 e_5 b_1 b_2)(\oplus e_1 e_4 b_0 b_3)(\oplus e_2 e_4) \\ & (\oplus e_2 e_5) (\oplus e_4 e_1)(\oplus e_5 e_1 e_3 b_9 b_{10}) \\ & (\oplus e_5 e_2 b_8 b_{11})) \end{aligned}$$

Rules of simplification S_1 and S_2 and theorem 2:

$$U_2 = (\perp (\oplus e_1 e_3 e_5)(\oplus e_1 e_4)(\oplus e_2 e_4)(\oplus e_2 e_5))$$

The two unfoldings of examples 1 and 2 have the same canonic form, they are *conflict-equivalent*: $U_1 \approx_{conf} U_2$

1) Reasoning about processes: Let us consider all the process p of U_2 : $(\oplus e_1 e_3 e_5), (\oplus e_1 e_4), \dots$

- $\forall p \in U_2$ whenever e_3 is present, e_1 is present.
- $\forall p \in U_2, \neg e_3 \perp (e_1 \oplus e_3 \oplus e_5)$

This is the algebraic definition of \prec . Finally, from this chain of conflicts, the following causality can be deduced:

$$e_3 \prec (e_1 \oplus e_5) \quad (16)$$

- A similar reasoning can be made:

$$\forall p \in U_2, \neg(e_1 \oplus e_5) \perp (e_1 \oplus e_3 \oplus e_5)$$

This is the algebraic definition of:

$$(e_1 \oplus e_5) \prec e_3 \quad (17)$$

Equations (16) and (17) express that there is a *strong link* between e_3 and the process $(e_1 \oplus e_5)$ but \prec is not well suited to encompass this relation. These two processes are like “intricated”.

- In the same manner:

$$\begin{aligned} & \neg e_2 \perp (e_2 \oplus e_4) \perp (e_2 \oplus e_5) \\ & \equiv_{dist} \neg e_2 \perp (e_2 \oplus (e_4 \perp e_5)) \\ & \equiv_{def} e_2 \prec (e_4 \perp e_5) \quad (18) \end{aligned}$$

e_2 leads to a conflict

$$\begin{aligned} & \neg e_1 \perp ((\oplus e_1 e_3 e_5) \perp (e_1 \oplus e_4)) \\ & \equiv_{dist} \neg e_1 \perp (e_1 \oplus ((e_3 \oplus e_5) \perp e_4)) \\ & \equiv_{def} e_1 \prec ((e_3 \oplus e_5) \perp e_4) \quad (19) \end{aligned}$$

Equations (18) and (19) show that e_1 and e_2 transform the chain of conflict in a unique conflict. New relations between events or processes can be introduced:

- Alliance relation: e_1, e_3 and e_5 are in “an alliance relation”. Every event of this set is enforced by the occurrence of the other events: $e_1 \oplus e_3$ enforces e_5 , $e_1 \oplus e_5$ enforces e_3 and $e_3 \oplus e_5$ enforces e_1 .
- Intrication: the occurrence of e_3 forces $e_1 \oplus e_5$ and reciprocally $e_1 \oplus e_5$ forces e_3 .
- Resolving conflicts (liberation):
 - e_1 resolves 3 conflicts on 4 (as e_2, e_4 and e_5)
 - e_3 resolves every conflicts.

Semantically, e_3 can be identified as an important event in the chain. Moreover, $(\oplus e_1 e_3 e_5)$ is a process aggregated with “associated events”. This chain of conflict can be seen as two causalities in conflicts: $(e_1 \prec (e_4 \perp (e_3 \oplus e_5))) \perp (e_2 \prec (e_4 \perp e_5))$

C. Example 3 (Cash dispenser)

Let us consider a cash dispenser illustrated in Figure 12. The user has three tries (3 tokens are generated in place WaitEnterCode) to enter a valid code (*OKcode*), then he can get *Cash* or can *Consult* its account. In this example, a reset arc from *OKCode* allow to clear the tokens that have not be consumed (for example when the user has entered a valid code at its first or second try) and two reset arcs have been added from *getConsult* and *getCash* to clear *ReadyToConsult* or *ReadyToGetCash*.

It could be useful to prove that if the events *GetCash* implies that *Okcode* belongs to the same process.

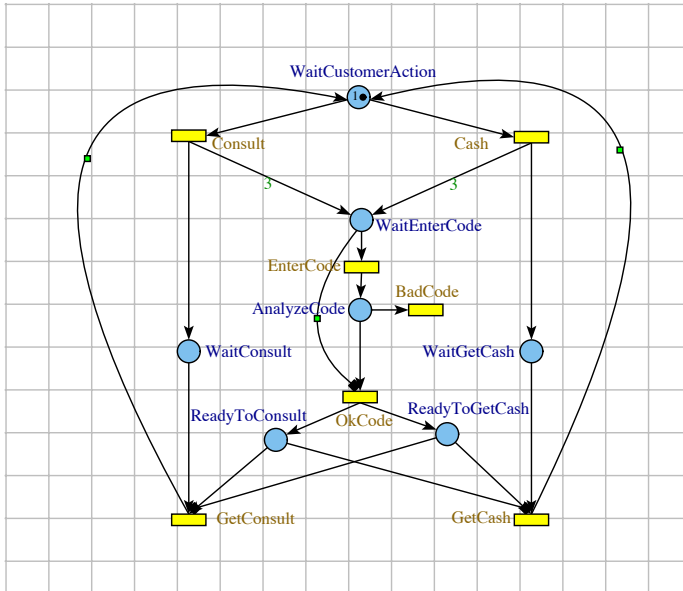


Figure 12. Cash dispenser.

The unfolding of cash dispenser is given in Figure 13. A combinatory inflation of the net is caused by to the reset arcs and by the transitions, *Consult* and *Cash*, which produces 3 tokens each.

The reset arcs introduces for each events $e_9, e_{10}, e_{11}, e_{18}, e_{19},$ and e_{20} (events relative the transition *OKcode*) two arcs, which consumes adding conditions. The translation of reset arcs have been defined manually and is not yet implemented in reduction rules. The computing of the canonical form of the processes is following expression:

$$\begin{aligned}
 U3 = & (\perp (\oplus \text{Consult EnterCode OKcode GetConsult})) \\
 & (\oplus \text{Consult EnterCode BadCode OKcode GetConsult}) \\
 & (\oplus \text{Consult EnterCode BadCode BadCode OKcode GetConsult}) \\
 & (\oplus \text{Consult EnterCode BadCode BadCode BadCode}) \\
 & (\oplus \text{Cash EnterCode OKcode Getcash})
 \end{aligned}$$

$$\begin{aligned}
 & (\oplus \text{Cash EnterCode BadCode OKcode Getcash}) \\
 & (\oplus \text{Cash EnterCode BadCode BadCode OKcode Getcash}) \\
 & (\oplus \text{Cash EnterCode BadCode BadCode BadCode})
 \end{aligned}$$

This expression formally proves that if *GetCash* is in a process then *OkCode* belongs to the same process.

VII. IMPLEMENTATION ASPECTS

A program [19] has been developed. It takes Petri Nets as inputs Romeo [20] unfolds and computes the canonical form. This program has been written in Lisp. The algebraic definitions and the reduction rules has been described with *redex*, a formal package introduced in [11].

A. Syntax of the language

The redex package allows to implement the syntactic rules of the language with an abstract and conceive way:

```

; Nodes
[bool t f]
[n variable bool b e (¬ ⊕ n)]
[e variable (¬ e)]
[b variable (¬ b)]
; n-ary or binary operators
[on ⊕ ⊥ {}]
[o2 <]
; Process
[P variable (⊕ Q ...)]
[Q variable P n]
[C-P (⊕ C-P P) (⊕ P C-P) hole]
; Conflicts
[X variable (⊥ Y ...)]
[Y variable X n]
[C-X (⊥ C-X P) (⊥ P C-X) hole]
; Expression
[E variable (on F ...)]
(b o2 e) (P o2 X)
[F variable E P]
[C-E (on C-E E) (on E C-E)
(E o2 C-E) (C-E o2 E) hole]

```

- The lines 2 to 5 define the basics nodes, which are boolean, b conditions and e the events. The term *variable* in lines 3 to 5 allows to use in the language every symbols denoted as n_i, b_i or e_i . These symbols are the terminal symbols of the alphabet.
- The lines 7 and 8 group the n-ary and the binary operators.
- Lines 10 to 12 define the process. A process P is constituted with \oplus operator on Q , where Q is defined as a node n or a process P . Every non terminal symbol P_i is a process.
- Lines 14 to 16 define conflicts in a similar way.
- Finally, lines 18 to 22 define expressions that are built from conflicts, process and causality.
- For every term: Process, Conflicts and Expression, contexts are defined. The contexts capture prefixes

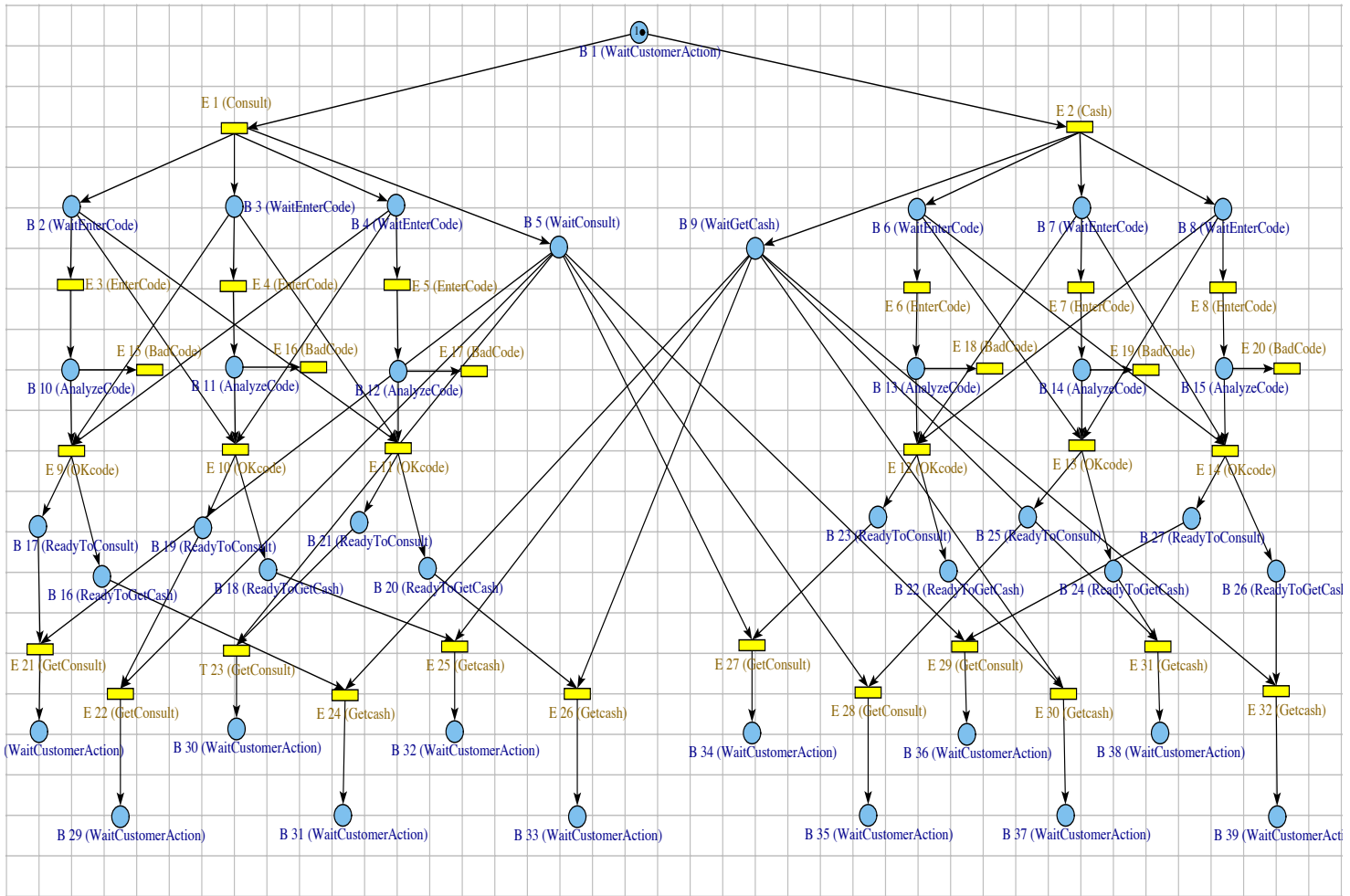


Figure 13. Unfolding of Cash dispenser.

and suffixes of an expression and put them into a hole.

B. Reductions rules

Definitions have been implemented as reduction rules:

```

(→ (in-hole C-P
    (⊕ Q_1 ... f Q_2 ...))
    (in-hole C-P f) "A⊕")
(→ (in-hole C-E
    (⊕ Q_1 ... e_1 Q_2 ... (¬ e_1) Q_4 ...))
    (in-hole C-E f) "F⊕")
    
```

The particularities of this syntax are:

- $Q_i...$ is equivalent to the regular expression Q_i^* , which represents an ordered list of symbol Q_i , which is eventually empty, finite or infinite.
- The contexts C-P or C-E allows to capture every sub-expression with every prefix and suffix.

The first rule, labelled A_{\oplus} , illustrates that f is an absorbing element. In this rule, C-P captures the context of a Process P and put into a hole. This reduction rule expresses that every sub-expression of the type $(\oplus Q_1...fQ_2...)$, which can

be reduced to the node f . This rule is named and thus, its use can be traced in a future proof.

The second rule F_{\oplus} states the property defined in Section IV-B4 : $e_1 \oplus \neg e_1 \equiv \#f$. This reduction rules defines that every expression (for every context C-E) containing e_1 and $\neg e_1$ in an \oplus operator can be reduced to f .

C. Theorems

This section describes the implementation and the coding of theorems.

1) *Theoreme 4*: Theorem 4 has been stated from definition 6, which corresponds to the following statements:

```

(define (U1n n 1)
  (if (>= (- (maxi 1) n) 2)
    (cons (list-ref 1 (+ n 2))
          (Rn (+ n 2) 1)) empty))
    
```

```

(define (V2n n 1)
  (if (>= (- (maxi 1) n) 3)
    (cons (list-ref 1 (+ n 3))
          (Rn (+ n 3) 1)) empty))
    
```

Finally, the implementation is coded like the union of the previous definitions:

```
(define (Rn n 1)
  (if (>= (- (maxi 1) n) 1)
      (Union (U1n n 1) (U2n n 1))
      empty))
```

Note that the implementation of the definitions and the theorems are closed to their formal expression.

2) *Theoreme 3*: $E \perp (E \oplus F) \equiv (E \oplus F)$ has been implemented has a reduction rule:

```
(--> (in-hole C-E
      (⊥ E_1 ... E E_2 ...
       (⊕ E E_3 ... ) E_4 ...))
      (in-hole C-E
      (⊥ E_1 ... E_2 ...
       (⊕ E E_3 ... ) E_4 ...)) "T3")
```

This code means that if E is in a “ \perp expression:” ($\perp E_1 \dots E E_2 \dots$), then if a sub expression in \oplus contains E , then E can be suppressed of the “ \perp expression” for any context.

VIII. CONCLUSION AND FUTURE WORK

This work is a first attempt to present an axiomatic framework to the analyze of the processes issued of an unfolding. From a set of axioms, distributivities, and derivation rules, theorems have been established and a reduction process can lead to a canonic form. The unfolding process, definitions, theorems, and reduction rules have been coded in LISP[21] with a package named PLT/Redex[11][22]. This canonic form assets an equivalence conflicts (\equiv_{conf}) between unfoldings and then Petri nets.

Several perspectives are into progress. First, new theorems have to be established allowing to speed up the procedure of canonic reduction and to extend extraction of knowledge on relationship between events. Different kinds of relationship between events can be defined and formalized: Alliance relation, Intrication, etc. Moreover, as already outlined in the examples, algebraic reasoning can raise semantic informations about events from the canonic form. Another perspective is to extend the approach to Petri nets with inhibitor or drain arcs.

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